

A sharp interface method for two-phase compressible flows at low-Mach regime

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Journée Des Doctorants du LIMSI



Introduction

Flows of interest

- Compressible gas & quasi-incompressible liquid
- surface tension & heat transfer & phase change

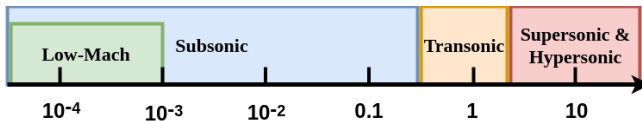


ocean wave



bubble growth near a heated plate

- liquid: low-Mach regime



Mach number ($Ma=u/c$) & Flow Regimes

Introduction

Previous studies

- incompressible liquid model [Tanguy et al., 2014] [Sato and Ničeno, 2013]
 - robust, efficient
 - **without compressible effects**
- compressible liquid model [Fechter et al., 2017][Faccanoni et al., 2012]
 - take compressible effects into account
 - **excessive numerical diffusion** Error $\propto 1/Ma$
 - **time step limitation** $\Delta t = \Delta x / \max(c + u)$

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Objective

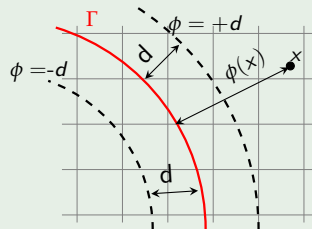
develop a compressible solver for both liquid and gas:

- Accurate at low-Mach regime
- Uniform time step with respect to the Mach number
- Well-balanced discretization of sources terms (gravity, surface tension)
- An accurate high-order method to capture the interface

Interface description

Level-Set method [Osher and Sethian, 1988]

- ϕ : signed distance function
- $|\nabla\phi| = 1$
- Normal vector $\mathbf{n} = \frac{\nabla\phi}{|\nabla\phi|} \Big|_{\phi=0}$
- interface Curvature $\kappa = \nabla \cdot \left(\frac{\nabla\phi}{|\nabla\phi|} \right)$
- Level-Set advection $\frac{\partial\phi}{\partial t} + \mathbf{u} \cdot \nabla\phi = 0$



Operators splitting

Governing equations

$$\begin{cases} \partial_t \rho + \nabla \cdot (\rho \mathbf{u}) = 0 \\ \partial_t (\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) + \nabla p = -\rho \nabla \psi + \nabla \cdot \boldsymbol{\tau}_{visc} + \sigma \kappa \mathbf{n} \delta(\phi) \\ \partial_t (\rho E) + \nabla \cdot ((\rho E + p) \mathbf{u}) = -\rho \mathbf{u} \cdot \nabla \psi + \nabla \cdot (\boldsymbol{\tau}_{visc} \mathbf{u}) + \sigma \kappa \mathbf{u} \cdot \mathbf{n} \delta(\phi) + \nabla \cdot (k \nabla T) \\ \partial_t \phi + \mathbf{u} \cdot \nabla \phi = 0 \end{cases}$$

$$E = e + \frac{|\mathbf{u}|^2}{2} \quad \rho e = \frac{p + \gamma \pi^\infty}{\gamma - 1} \quad p = \rho r T - \gamma \pi^\infty \quad r = c_p - c_v \quad \gamma = c_p / c_v$$

ψ : gravitational potential $\boldsymbol{\tau}_{visc}$: viscous tensor

κ : interface Curvature k : thermal conductivity

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Acoustic / Transport / Diffusion decomposition

$$\begin{cases} \partial_t \rho + \rho \nabla \cdot \mathbf{u} + \mathbf{u} \cdot \nabla \rho = 0 \\ \partial_t (\rho \mathbf{u}) + \rho \mathbf{u} \nabla \cdot \mathbf{u} + \nabla p + \mathbf{u} \cdot \nabla (\rho \mathbf{u}) = -\rho \nabla \psi + \sigma \kappa \mathbf{n} \delta(\phi) + \nabla \cdot \boldsymbol{\tau}_{visc} \\ \partial_t (\rho E) + \rho E \nabla \cdot \mathbf{u} + \nabla \cdot (\rho \mathbf{u}) + \mathbf{u} \cdot \nabla (\rho E) = -\rho \mathbf{u} \cdot \nabla \psi + \sigma \kappa \mathbf{u} \cdot \mathbf{n} \delta(\phi) + \nabla \cdot (\boldsymbol{\tau}_{visc} \mathbf{u}) + \nabla \cdot (k \nabla T) \\ \partial_t \phi + \mathbf{u} \cdot \nabla \phi = 0 \end{cases}$$

Numerical resolution

① Acoustic system

- perform a **Suliciu-type relaxation** to deal with any equation of state and obtain **linearly degenerate system** [Bouchut, 2004]
- resolve the Riemann problem that takes the source term (gravity) and jump conditions related to **surface tension** & **phase change (future work)** into account in a consistent way
- **well-balanced scheme** for gravity and surface tension : discretization at cell face or interface
- **low-Mach correction**: the accuracy of the global scheme independent from Mach number [Chalons et al., 2016]
- **implicit scheme**: $\Delta t = \Delta x / \max(|u|)$ (**future work**)

② Transport system

- sharp interface & avoid mixing cell: **ghost fluid method**
- Level-Set advection: **One-Step (OS) scheme** [Daru and Tenaud, 2004]
coupled time-space approach: same order accuracy at time & space

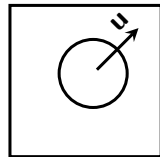
③ Diffusion system (viscous & heat transfer)

- classical finite volume discretization

Numerical test

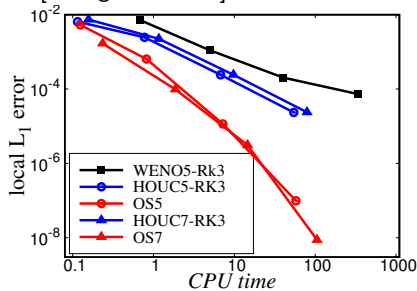
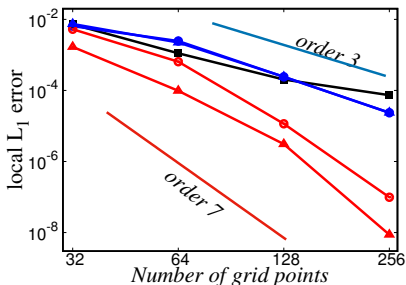
Circle advection

- advection in diagonal direction with a periodic boundary condition
- $t=100$ (100 periods) $CFL=0.5$
- local L_1 error ($|\phi| \leq 3\Delta x$)



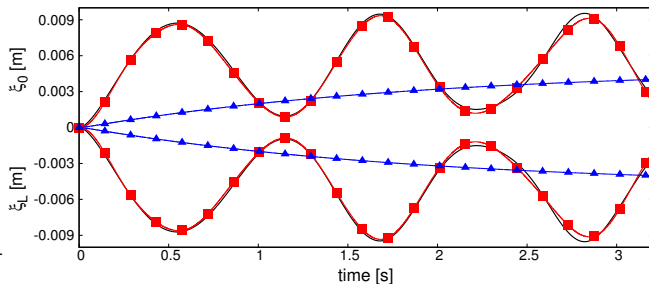
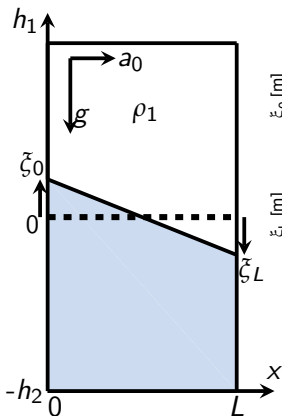
Numerical scheme

- Coupled time-space approach: high-order **One-Step (OS)** scheme
- Separate time-space approach: **WENO-RK** [Jiang and Shu, 1996]
Houc (High-Order upwind centered)-**RK** [Nourgaliev, 2007]



Two-dimensional sloshing [Chanteperdrix, 2004]

- $\rho_2/\rho_1 = 1000$ $h_1/L = 1.25$ $h_2/L = 1$
- $c_1 \approx 370\text{m/s}$ $c_2 \approx 1500\text{m/s}$ $Ma_{\max} \approx 2 \times 10^{-5}$
- $a_0/g = 0.01$ resolution : $L/\Delta x = 40$

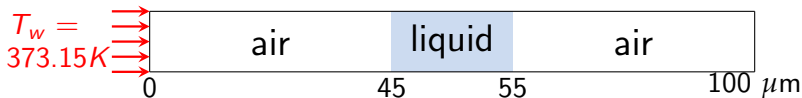


— analytical solution: linearized potential theory

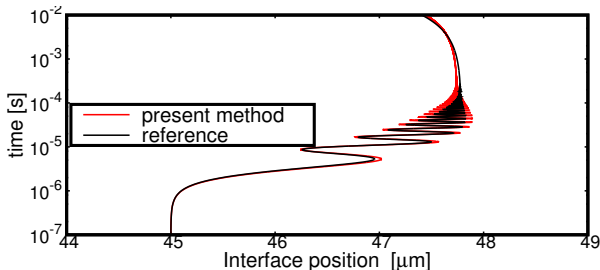
■ with low-Mach correction

▲ without low-Mach correction

1D non-isothermal problem



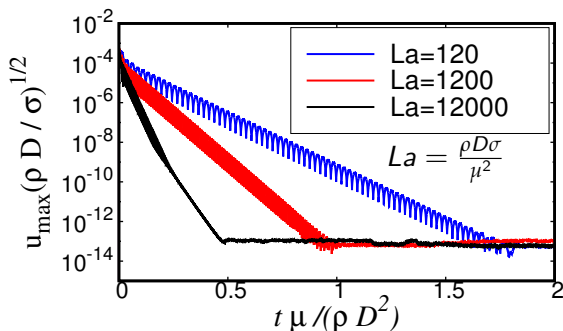
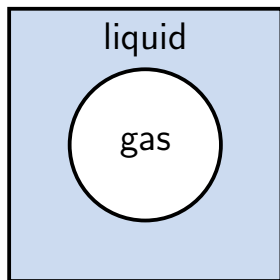
- $T_{liq} = T_{air} = 293.15K$
- liquid: $\rho = 1000 kg/m^3$ $c = 1500 m/s$ $c_p = 4184 JK^{-1}kg^{-1}$
 $k = 0.6 Wm^{-1}K^{-1}$ $\mu = 1.82 \times 10^{-5} Pa s$
- air: $\rho = 1.204 kg/m^3$ $c = 340 m/s$ $c_p = 1004.5 JK^{-1}kg^{-1}$ $k = 0.0256 Wm^{-1}K^{-1}$ $\mu = 0.001 Pa s$



Trajectories of left interface: reference [Daru et al., 2010]

Parasitic currents

- liquid $\rho = 1$ $c = 20$ p_l
- gas $\rho = 1$ $c = 1$ $p_g = p_l + \sigma\kappa$

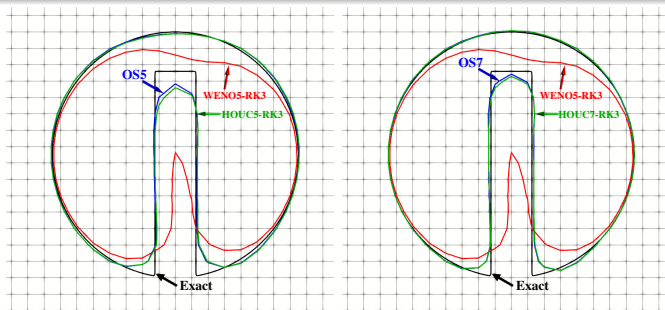


Evolution of velocity fluctuations of a 2D bubble in a slightly compressible liquid with different Laplace numbers by varying the fluid viscosity ($R = 12.8 \triangle x$)

Numerical test

Zalesak disk

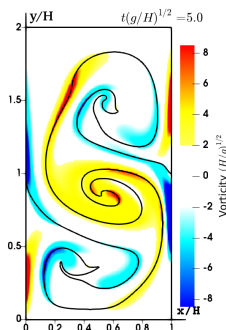
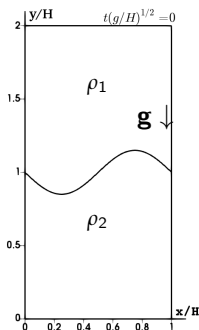
- disk with a rectangular slot
- Rotating velocity field: $u = \pi(50 - y)/314$ $v = \pi(x - 50)/314$
- one full rotation CFL=0.5



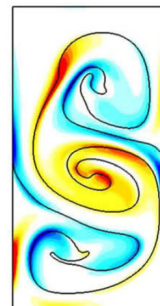
*Interface representation of the Zalesak disk after one full rotation
resolution: 50×50*

Rayleigh-Taylor instabilities

- $\rho_1 = 1.8$ $\rho_2 = 1$ $Ma_{\max} \approx 10^{-2}$
- $Re = \sqrt{(H/2)^3/g/\nu} = 420$ Mesh : 312×624



(a)



(b)

Vorticity and interface representation: (a) present Level-Set formulation
 (b) incompressible Level-Set formulation [Colicchio, 2004]

Thank you for your attention !

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